

Kalchereiss Chapters 1.2 and 1.3

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Where all this is heading

Path-integral approach is based on ordinary complex functions and not operators.

Basic tools are

- Equations from classical mechanics, especially involving the Lagrangian and sometimes the Hamiltonian
- Methods of differential equations, especially
 - Linear, second-order with small higher-order terms
 - Perturbative expansions for the higher-order terms
 - Green's functions for a delta-function source
 - Correlation functions as derived from functional dependence on general source terms
- What we won't need (*except for initial setup of the path-integral formalism*)
 - Operator theory
 - Commutation relations
 - Eigenvectors and eigenvalues
- Really???
 - Nahhhh But for many of the interesting results of field theory, this 'traditional' quantum mechanics stuff takes a back seat

Green's functions are useful for solving Euler-Lagrange equations

(non-rigorous, non-engineering)

Notation: $\square\varphi \equiv \frac{\partial^2\varphi}{\partial t^2} - \frac{\partial^2\varphi}{\partial x^2}$

Simple equation: $\square\varphi = J$

Formal solution: $\varphi = \square^{-1}J$; \square^{-1} is called a **Green's function**. Often, J is a delta-function.

Perturbation theory (preliminary to Feynman diagrams)

Add a small term to the simple equation. $\square\varphi(\lambda, t, x) - \lambda\varphi^2(\lambda, t, x) = J(t, x)$. The solution depends on the small parameter λ .

Expand the solution in powers of λ . $\varphi = \varphi(\lambda, t, x) = \varphi_0(t, x) + \lambda\varphi_1(t, x) + \lambda^2\varphi_2(t, x) + \dots$

The general solution is $\varphi(\lambda, t, x) = \square^{-1}[J(t, x) + \lambda\varphi^2(\lambda, t, x)]$

$\varphi_0(t, x) = \varphi|_{\lambda=0} = \varphi(0, t, x)$; solution is $\varphi_0 = \square^{-1}J$

$$\varphi_1(t, x) = \frac{\partial\varphi}{\partial\lambda}\bigg|_{\lambda=0} = \frac{\partial}{\partial\lambda}\square^{-1}[J(t, x) + \lambda\varphi^2(\lambda, t, x)]\bigg|_{\lambda=0} = \frac{\partial}{\partial\lambda}\square^{-1}[\lambda\varphi^2(\lambda, t, x)]\bigg|_{\lambda=0} = \square^{-1}[\varphi^2(0, t, x)] = \square^{-1}[(\varphi_0)^2(t, x)]$$

So $\varphi_1(t, x) = \square^{-1}[\square^{-1}J\square^{-1}J]$

$$2\varphi_2 = \frac{\partial^2\varphi}{\partial\lambda^2}\bigg|_{\lambda=0} = \frac{\partial^2}{\partial\lambda^2}\square^{-1}[J(t, x) + \lambda\varphi^2(\lambda, t, x)]\bigg|_{\lambda=0} = \square^{-1}[4\varphi_0(t, x)\varphi_1(t, x)]$$

So $\varphi_2 = 2\square^{-1}(\square^{-1}J\square^{-1}[\square^{-1}J\square^{-1}J])$

What is \square^{-1} ? It's easiest to introduce this for a 1D problem.

(Following Kachelriess with $m=1$)

Notation: $Dx \equiv \frac{d^2x}{dt^2} + \omega^2x$

Simple equation: $Dx = J$

Formal solution: $x = D^{-1}J$; D^{-1} is called a Green's function and written as G . Often, J is a delta-function.

What does $x = D^{-1}J$ mean? $x(t) = \int dt' D^{-1}(t, t')J(t')$ It's like matrix multiplication.

Kachelriess derives D^{-1} (equation 1.34) (I use D^{-1} instead of G). $D^{-1}(t, t') = \int \frac{d\Omega}{2\pi} \frac{e^{-i\Omega(t-t')}}{\omega^2 - \Omega^2}$

First verify this is right. **We want to show that $DD^{-1}J = J$.**

$$D(D^{-1}J) = \left(\frac{d^2}{dt^2} + \omega^2 \right) \int dt' \int \frac{d\Omega}{2\pi} \frac{e^{-i\Omega(t-t')}}{\omega^2 - \Omega^2} J(t') = \int dt' \int \frac{d\Omega}{2\pi} \frac{(\omega^2 - \Omega^2)e^{-i\Omega(t-t')}}{\omega^2 - \Omega^2} J(t') = \int dt' \delta(t' - t) J(t') = J(t)$$

using $\frac{d^2}{dt^2} e^{-i\Omega(t-t')} = -\Omega^2 e^{-i\Omega(t-t')}$ and $\int \frac{d\Omega}{2\pi} e^{-i\Omega(t-t')} = \delta(t - t')$

Unfortunately, $D^{-1}(t, t') = \int \frac{d\Omega}{2\pi} \frac{e^{-i\Omega(t-t')}}{\omega^2 - \Omega^2}$ is NOT well-defined! The integrand diverges at $\Omega = \pm\omega$.

Resolve this by adding $\pm i\varepsilon$ to the denominator, integrating with Cauchy's residue theorem and taking ε to 0. Still satisfies $DD^{-1}J = J$ but you get different D^{-1} (negative leads to the retarded Green's function) depending on the sign of $\pm i\varepsilon$ and thus different solutions. Impose causality to pick the right sign (retarded).

Problem 1.8a

Show $\vartheta(t) = -\frac{1}{2\pi i} \lim_{\varepsilon \rightarrow 0^+} \int_{-\infty}^{+\infty} d\omega \frac{e^{-i\omega t}}{\omega + i\varepsilon}$ where $\vartheta(t) = 0$ if $t < 0$ and $\vartheta(t) = 1$ if $t > 0$

Calculus of residues: $\mathbf{t < 0}$, choose upper contour.

$$\frac{e^{-i\omega t}}{\omega} = \frac{e^{i|t|R(\cos\theta + i \sin\theta)}}{R(\cos\theta + i \sin\theta)} = \frac{e^{i|t|R\cos\theta} e^{-|t|R \sin\theta}}{R(\cos\theta + i \sin\theta)}$$

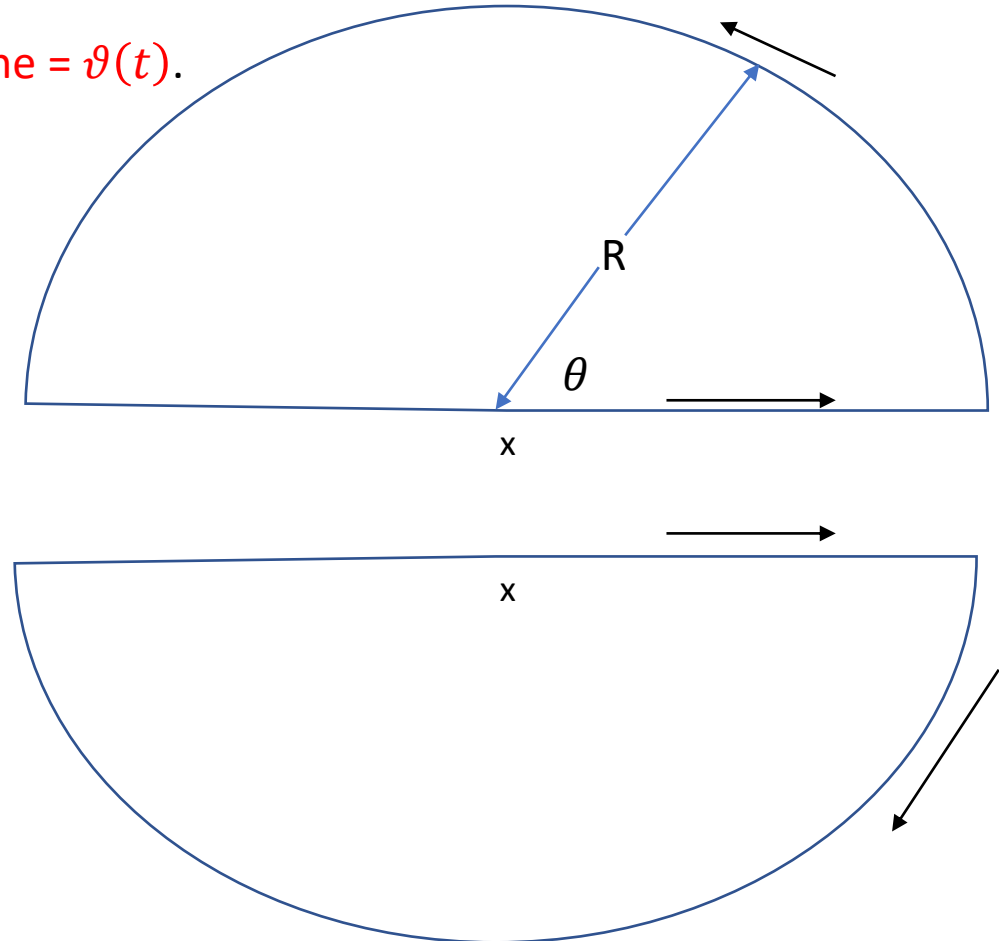
goes to 0 as $R \rightarrow \infty$

The integral on the entire semicircle ($R \rightarrow \infty$) = **integral on real line = $\vartheta(t)$** .

But there is no pole within the semicircle so total **integral = 0**.

When $\mathbf{t > 0}$, choose the lower contour and as before, the integral on the curve is 0. However, there is a pole in the semicircle. The residue at $\omega = -i\varepsilon$ is $e^{-\varepsilon t}$
Cauchy's theorem says the integral's value is so

$$\vartheta(t) = \frac{-1}{2\pi i} \lim_{\varepsilon \rightarrow 0^+} (-2\pi i) e^{-\varepsilon t} = 1$$



Takeaways

- Perturbation theory has lots of terms with \square^{-1} . Turns out you can draw diagrams where J is a vertex and \square^{-1} is a line. (*Like Feynman diagrams*)
- Each \square^{-1} involves an integral with a quadratic term in the denominator. (*Like Feynman propagator*)
- You need to pick which \square^{-1} you want. Requires adding $\pm i\varepsilon$ to the denominator. Causality implies $+i\varepsilon$.

Relativity

$$x^\mu = (t, x, y, z)$$

$$x_\mu = (t, -x, -y, -z)$$

Frame transformations for motion in the x-direction are

$$x'(x, y, z, t) = \gamma(v)(x + vt) \dots \text{ where } \gamma(v) = \frac{1}{\sqrt{1-v^2}}$$

$$t'(x, y, z, t) = \gamma(v)(t + vx)$$

$$y'(x, y, z, t) = y$$

$$z'(x, y, z, t) = z$$

$x^\mu x_\mu \equiv \sum_{\mu=0}^3 x^\mu x_\mu$ is frame-invariant. **Similarly with other 4-vectors.**

This can be generalized to multi-index objects.

Our senses are frame-invariant so **ultimately** the things we measure must be frame-invariant. Such variables are called **scalars**. $x^\mu x_\mu$ is a scalar.